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ROS Manipulation is the term used to refer to any robot that manipulates something in its environment. The main goal of this Course is to teach you the basic tools you need to know in order to be able to understand how ROS Manipulation works, and teach you how to implement it for any manipulator robot.

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About The Book. ROS in 5 days is the book associated with a course giving you the basic tools and knowledge to be able to understand and create any basic ROS-related project. You will be able to move robots, read their sensor data, do parallel tasks, see visual representations of complex data and much more. This course is divided into two main parts.

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